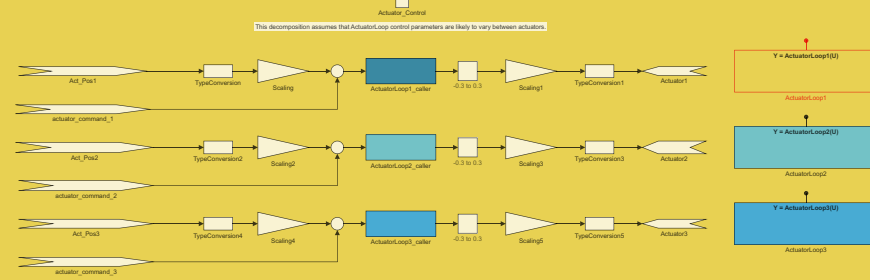


[Actuator1,Actuator2,Actuator3] = Actuator_Control(Act_Pos1,actuator_command_1,Act_Pos2,actuator_command_2,Act_Pos3,actuator_command_3)



Actuator_Control